

Detailed and Complete Listing of Claims:

1. (Cancelled)

2. (Previously Amended) A robot, comprising:

receiver means for receiving a new robot control program module from a communication line;

register means for adding the new robot control program module received by the receiver means to the robot;

selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module added to the robot; and

control program executor means for executing the robot control program module selected by the selector means.

3. (Previously Amended) The robot, in accordance with claim 2, further comprising an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module,

the initialization program determining an execution point of time of the new robot control program module.

4. (Previously Amended) The robot in accordance with claim 2, further comprising an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

5. (Previously Amended) The robot in accordance with claim 2, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

6. (Previously Amended) The robot in accordance with claim 2, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

7. (Previously Amended) The robot in accordance with claim 2, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof; the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

8. (Previously Amended) A robot, comprising:

a receiver means for receiving a new robot control program module from a communication line;

a register means for adding the new robot control program module received by the receiver means to the robot;

a selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module added to the robot; and

a control program executor means for executing the robot control program module selected by the selector means; and the receiver means uses an internet as the communication line and receives the new robot control program module by the internet.

9. (Previously Amended) The robot, in accordance with claim 8, further comprising an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the control program module,

the initialization program determining an execution point of time of the new robot control program module.

10. (Previously Amended) The robot in accordance with claim 8, further comprising an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

11. (Previously Amended) The robot in accordance with claim 8, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

12. (Previously Amended) The robot in accordance with claim 8, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

13. (Previously Amended) The robot in accordance with claim 8, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof; the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

14. (Cancelled)

15. (Previously Amended) A robot control system, comprising:

receiver means for receiving a new robot control program module from a communication line;

register means for adding the new robot control program module received by the receiver means to the robot control system;

selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot control system and the new robot control program module added to the robot control system; and

control program executor means for executing the robot control program module selected by the selector means.

16. (Previously Amended) The robot control system, in accordance with claim 15, further comprising

an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module,

the initialization program determining an execution point of time of the new robot control program module.

17. (Previously Amended) The robot control system in accordance with claim 15, further comprising

an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

18. (Previously Amended) The robot control system in accordance with claim 15, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

19. (Previously Amended) The robot control system in accordance with claim 15, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

20. (Previously Amended) The robot control system in accordance with claim 15, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof;

the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

21. (Previously Amended) A robot control system, comprising:

a receiver means for receiving a new robot control program module from a communication line;

a register means for adding the new robot control program module received by the receiver means to the robot control system;

a selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot control system and the new robot control program module added to the robot control system; and

a control program executor means for executing the robot control program module selected by the selector means; and

the receiver means uses an internet as the communication line and receives the new robot control program module by the internet.

22. (Previously Amended) The robot control system, in accordance with claim 21, further comprising

an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

the initialization program determining an execution point of time of the new robot control program module.

23. (Previously Amended) The robot control system in accordance with claim 21, further comprising

an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

24. (Previously Amended) The robot control system in accordance with claim 21, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

25. (Previously Amended) The robot control system in accordance with claim 21, further comprising

a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

26. (Previously Amended) The robot control system in accordance with claim 21, further comprising

a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof;

the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

27. (Cancelled)

28. (Previously Amended) A program storage medium storing a program which, when executed on a computer controlling a robot, causes said computer to perform the steps of:

receiving a new robot control program module from a communication line;

registering the received new robot control program module in the robot;

selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module received by the robot; and



executing the selected robot control program module.

29. (Previously Amended) A program storage medium storing a program in accordance with claim 28, wherein the receiving step uses an internet as the communication line and receives the new robot control program module by electronic mail.

30. (Previously Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of making the computer execute an initialization program execution step,

the initialization program execution step executing an initialization program included in the new robot control program module when the new robot control program module is registered in the robot.

31. (Previously Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of making the computer execute an initialization program execution step and a voice recognition word adder step,

the initialization program execution step executing an initialization program included in the new robot control program module when the new robot control program module is registered in the robot;

the voice recognition word adder step adding voice recognition words to a voice recognizer dictionary;

the voice recognition words being used to call the new robot control program module registered by the registering step.

32. (Previously Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of making the computer execute a voice recognition word adder step,

the voice recognition word adder step adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the registering step.

33. (Previously Amended) The program storage medium storing a program in accordance with claim 28, further comprising the step of making the computer execute a received program executing step of executing the new robot control program module at the reception thereof in the receiving step.

34. (Previously Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of

executing the new robot control program module at the reception thereof in the receiving step; and

erasing the new robot control program module after having executed the new robot control program module.

35. (Previously Amended) A program storage medium storing a program which, when executed on a computer controlling a robot, causes said computer to perform the steps of:

receiving a new robot control program module from a communication line;

registering the received new robot control program module in the robot;

selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module received by the robot; and

executing the selected robot control program module; and

wherein the receiving step includes using an internet as the communication line.

36. (Previously Amended) The program storage medium storing a program in accordance with claim 35, further comprising the steps of making the computer execute an initialization program execution step,

the initialization program execution step executing an initialization program included in the new robot control program module when the new robot control program module is registered in the robot

the initialization program determining an execution point of time of the new robot control program module.

37. (Previously Amended) The program storage medium storing a program in accordance with claim 35, further comprising the steps of making the computer execute an initialization program execution step and a voice recognition word adder step,

the initialization program execution step executing an initialization program included in the new robot control program module when the new robot control program module is registered in the robot;

the voice recognition word adder step adding voice recognition words to a voice recognizer dictionary;

the voice recognition words being used to call the new robot control program module registered by the registering step.

38. (Previously Amended) The program storage medium storing a program in accordance with claim 35, further comprising the step of making the computer execute a received program executing step of executing the new robot control program module at the reception thereof in said receiving step.

39. (Previously Amended) The program storage medium storing a program in accordance with claim 35, further comprising the step of making the computer execute a received program executing step of executing the new robot control program module at the reception thereof in said receiving step wherein;

the received program executing step includes erasing, after having executed the new robot control program module.

40. (Previously) A robot, comprising:

a receiver for receiving a new robot control program module from a communication line;

a register for adding the new robot control program module received by the receiver to the robot;

a selector for selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module added to the robot; and

a control program executor for executing the robot control program module selected by the selector.

41. (Previously Added) The robot, in accordance with claim 40, further comprising an initialization program executor for executing an initialization program included in the new robot control program module registered by the register, at the registration of the new robot control program module,

the initialization program determining an execution point of time of the new robot control program module.

42. (Previously Added) The robot in accordance with claim 40, further comprising an initialization program executor for executing an initialization program included in the new

robot control program module registered by the register, at the registration of the new robot control program module; and

a voice recognition word adder for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register.

43. (Previously Added) The robot in accordance with claim 40, further comprising

a voice recognition word adder for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register.

44. (Previously Added) The robot in accordance with claim 40, further comprising a received program executor for executing the new robot control program module received by the receiver, at the reception thereof.

45. (Previously Added) The robot in accordance with claim 40, further comprising a received program executor for executing the new robot control program module received by the receiver, at the reception thereof; the received program executor erases, after having executed the new robot control program module, the new robot control program module.